

Number Sets. An expression such as $k \in \mathbb{N}$ (read as “ k is an element of \mathbb{N} ” or “ k in \mathbb{N} ”) means that k is a natural number; a *natnum*.

\mathbb{N} = natural numbers = $\{0, 1, 2, \dots\}$.

\mathbb{Z} = integers = $\{\dots, -2, -1, 0, 1, \dots\}$. For the set $\{1, 2, 3, \dots\}$ of positive integers, the *posints*, use \mathbb{Z}_+ . Use \mathbb{Z}_- for the negative integers, the *negints*.

\mathbb{Q} = rational numbers = $\{\frac{p}{q} \mid p \in \mathbb{Z} \text{ and } q \in \mathbb{Z}_+\}$. Use \mathbb{Q}_+ for the positive *ratnums* and \mathbb{Q}_- for the negative ratnums.

\mathbb{R} = reals. The *posreals* \mathbb{R}_+ and the *negreals* \mathbb{R}_- .

\mathbb{C} = complex numbers, also called the *complexes*.

An “*interval of integers*” [$b..c$] means the intersection $[b, c] \cap \mathbb{Z}$; ditto for open and closed intervals. So $[e..2\pi] = \{3, 4, 5, 6\} = [3..6] = (2..6]$. We allow b and c to be $\pm\infty$; so $(-\infty..-1]$ is \mathbb{Z}_- .

Mathematical objects. Seq: ‘*sequence*’. poly(s): ‘*polynomial(s)*’. irred: ‘*irreducible*’. Coeff: ‘*coefficient*’ and var(s): ‘*variable(s)*’ and parm(s): ‘*parameter(s)*’. Expr.: ‘*expression*’. Col: ‘*Constant of Integration*’. Lol: ‘*Limit(s) of Integration*’.

Fnc: ‘*function*’ (so ratfnc: means rational function, a ratio of polynomials). cty: ‘*continuity*’. cts: ‘*continuous*’. diff’able: ‘*differentiable*’.

Soln: ‘*Solution*’. Thm: ‘*Theorem*’. Prop’n: ‘*Proposition*’. CEX: ‘*Counterexample*’. eqn: ‘*equation*’. RhS: ‘*RightHand Side*’ of an eqn or inequality. LhS: ‘*left-hand side*’. Sqrt or Sroot: ‘*square-root*’, e.g, “the sroot of 16 is 4”. Ptn: ‘*partition*’, but pt: ‘*point*’, as in “a fixed-pt of a map”.

FTC: ‘*Fund. Thm of Calculus*’. IVT: ‘*intermediate-Value Thm*’. MVT: ‘*Mean-Value Thm*’. CoV: ‘*Change-of-Variable*’.

Phrases. WLOG: ‘*Without loss of generality*’. TFAE: ‘*The following are equivalent*’. ITOF: ‘*In Terms Of*’. OTForm: ‘*of the form*’. FTSOC: ‘*For the sake of contradiction*’. Use iff: ‘*if and only if*’.

IST: ‘*It Suffices to*’ as in ISTShow, ISTExhibit.

Use w.r.t: ‘*with respect to*’ and s.t: ‘*such that*’.

Latin: e.g: *exempli gratia*, ‘*for example*’. i.e: *id est*, ‘*that is*’. QED: *quod erat demonstrandum*, meaning “end of proof”.

LinA quizzes so far...

Q0: ^{Mon. 31,Aug} The **slope** of line $3[y - 5] = 2[x - 2]$ is

Point $(-4, y)$ lies on this line, where $y =$

Let $y = f(x) := [5 + \sqrt[3]{x}]/2$. Its inverse-function is $f^{-1}(y) =$

Q1: ^{Wed. 09Sep} *Henceforth*, let *AT* mean “Always True”, *AF* mean “Always False” and *Nei* mean “Neither always true nor always false”. Below, $\mathbf{u}, \mathbf{v}, \mathbf{w}$ repr. *distinct, non-zero* vectors in \mathbb{R}^4 , a \mathbb{R} -VS. Please circle the correct response:

y1 If $\mathbf{w} \in \text{Spn}\{\mathbf{u}, \mathbf{v}\}$ then $\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$ is linearly independent. AT AF Nei

y2 If $\mathbf{w} \notin \text{Spn}\{\mathbf{u}, \mathbf{v}\}$ then $\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$ is linearly independent. AT AF Nei

y3 Collection $\{\mathbf{0}, \mathbf{w}\}$ is linearly-indep. AT AF Nei

y4 $\text{Spn}\{\mathbf{u}, \mathbf{v}, \mathbf{w}, \mathbf{u} + 2\mathbf{v} + 3\mathbf{w}\}$ is all of \mathbb{R}^4 . AT AF Nei

y5 If none of $\mathbf{u}, \mathbf{v}, \mathbf{w}$ is a multiple of the other vectors, then $\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$ is linearly independent. AT AF Nei

Q2: ^{Fri. 18Sep} A system of 3 linear equations in unknowns x_1, \dots, x_5 reduces to the augmented matrix

$$\left[\begin{array}{ccccc|c} 1 & 1 & 0 & 0 & 1 & 12 \\ 0 & 0 & 1 & 0 & -8 & 34 \\ 0 & 0 & 0 & 1 & 5 & -56 \end{array} \right], \text{ which is in RREF. Please } \spanstyle{\border: 1px solid black; padding: 2px;">circle} \text{ each pivot entry.}$$

OYOP, describe the *general solution* in this form,

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} ? \\ ? \\ ? \\ ? \\ ? \end{bmatrix} + \alpha \begin{bmatrix} ? \\ ? \\ ? \\ ? \\ ? \end{bmatrix} + \beta \begin{bmatrix} ? \\ ? \\ ? \\ ? \\ ? \end{bmatrix} + \gamma \begin{bmatrix} ? \\ ? \\ ? \\ ? \\ ? \end{bmatrix} + \dots$$

where each $\alpha, \beta, \gamma, \delta, \dots$ is a free variable (either x_1 or... or x_5), and each column vector has specific numbers in it. $\text{Dim}(\text{SolnFlat}) =$

Q3: ^{Wed. 30Sep} Inverse of $\begin{bmatrix} 3 & 1 & 0 \\ 5 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$ is

$$\left[\begin{array}{ccc} & & \\ & & \\ & & \end{array} \right].$$

Q4: ^{Mon. 05Oct} Let R_θ be the std. rotation [by θ] matrix. With

$$C := \begin{bmatrix} \sqrt{3} & -1 \\ 1 & \sqrt{3} \end{bmatrix} \quad \text{and} \quad B := \begin{bmatrix} \sqrt{2} & -\sqrt{2} \\ \sqrt{2} & \sqrt{2} \end{bmatrix},$$

the product $[CB]^{22} = \alpha \cdot R_\theta$, with $\alpha = \dots \in \mathbb{R}_+$
 and $\theta = \dots \in (-180^\circ, 180^\circ]$. [Hint: Don't multiply matrices. Geometrically, C and B represent what linear-trns?]

Q5: ^{Tue. 06Oct} Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ rotate the plane CCW by 60° , then vertically stretch by a factor of 5. W.r.t the std basis,

$$[T]_{\mathcal{E}}^{\mathcal{E}} = \begin{bmatrix} | & | \\ \hline | & | \\ | & | \end{bmatrix}.$$

Q6: ^{Tue. 20Oct} Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by $T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) := \begin{bmatrix} 3x - y \\ 2x + 6y \end{bmatrix}$. W.r.t ordered-basis $\mathcal{B} := \left(\begin{bmatrix} 5 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \end{bmatrix}\right)$, let $M := [T]_{\mathcal{B}}^{\mathcal{B}}$. Then $M = RTR^{-1}$,

where $R = \begin{bmatrix} | & | \\ \hline | & | \\ | & | \end{bmatrix}$, $M = \begin{bmatrix} | & | \\ \hline | & | \\ | & | \end{bmatrix}$.

Q7: ^{Tue. 20Oct} In \mathbb{R}^3 , the closest point to $\mathbf{v} := (1, 2, 3)$ on the line through $\mathbf{0}$ and $\mathbf{q} := (-2, 7, 0)$, is $\alpha\mathbf{q}$, where $\alpha = \dots$

In \mathbb{R}^2 , with $\mathbf{s} := (1, 8)$ and $\mathbf{w} := (4, -2)$, compute $\text{Orth}_{\mathbf{w}}(\mathbf{s}) = \dots$

Q8: ^{Mon. 30Nov} Let $B := \begin{bmatrix} 1 & 2 & 1 & 0 & 1 \\ 3 & 6 & 0 & -3 & 0 \end{bmatrix}$. Then $R := RREF(B)$ is [show no work, here]

$$R = \begin{bmatrix} | & | & | & | & | \\ \hline | & | & | & | & | \\ | & | & | & | & | \end{bmatrix}.$$

I For subspace $\mathbf{V} := \text{Nul}(L_B)$, use back-substitution, and *scaling*, to produce an *integer basis*

$$\mathbf{v}_1 := \left(\begin{array}{c} \dots \\ \dots \\ \dots \\ \dots \\ \dots \end{array} \right), \quad \mathbf{v}_2 := \left(\begin{array}{c} \dots \\ \dots \\ \dots \\ \dots \\ \dots \end{array} \right),$$

$$\mathbf{v}_3 := \left(\begin{array}{c} \dots \\ \dots \\ \dots \\ \dots \\ \dots \end{array} \right), \quad \mathbf{v}_4 := \left(\begin{array}{c} \dots \\ \dots \\ \dots \\ \dots \\ \dots \end{array} \right).$$

[Note: Only use as many as the dimension of \mathbf{V} .]

II Apply Gram-Schmidt to compute an **orthogonal integer-basis** for \mathbf{V} :

$$\mathbf{b}_1 := \left(\begin{array}{c} \dots \\ \dots \\ \dots \\ \dots \\ \dots \end{array} \right), \quad \mathbf{b}_2 := \left(\begin{array}{c} \dots \\ \dots \\ \dots \\ \dots \\ \dots \end{array} \right),$$

$$\mathbf{b}_3 := \left(\begin{array}{c} \dots \\ \dots \\ \dots \\ \dots \\ \dots \end{array} \right), \quad \mathbf{b}_4 := \left(\begin{array}{c} \dots \\ \dots \\ \dots \\ \dots \\ \dots \end{array} \right).$$

[Entries are integers]
 Arrange that the Gcd of the entries in each vector is 1, and that the first non-zero value is positive.

Q9: ^{Tue. 08Dec} Line $y = [\dots]x + \dots$ is the least-squares best-fit to data pts $\{(-2, 0), (-1, 0), (1, 0), (2, 1)\}$.

That's All, Folks!