

Differentiating a bilinear function

Jonathan L.F. King
University of Florida, Gainesville FL 32611-2082, USA
squash@ufl.edu
Webpage <http://squash.1gainesville.com/>
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(Below, use *VS* for vector space, and *IPS* for inner-product space.)

Prolegomenon. In this pamphlet, all VSes are *real* VSes, \mathbb{R} -VSes, as I don't wish to discuss what \mathbb{C} -differentiation means.

The Product Rule from calculus states:

Suppose $f, g: \mathbb{R} \rightarrow \mathbb{R}$ are differentiable. Then so

1a: is their product, and

$$[f \cdot g]' = [f \cdot g'] + [f' \cdot g].$$

It turns out this generalizes.

For an \mathbb{R} -IPS \mathbf{V} : Suppose $f, g: \mathbb{R} \rightarrow \mathbf{V}$ are

1b: diff'able fncs. Then so is $\langle f, g \rangle$, and

$$\langle f, g \rangle' = \langle f, g' \rangle + \langle f', g \rangle.$$

Also, for Physics problems in 3-dim'al Euclidean space:

Suppose $f, g: \mathbb{R} \rightarrow \mathbb{R}^3$ are diff'able. Then so is

1c: $\langle f, g \rangle$. Moreover,

$$\langle f \times g \rangle' = \langle f \times g' \rangle + \langle f' \times g \rangle.$$

All these raise the question (*not* "Beg the question", which means something different): What does it *mean* for a fnc $\mathbb{R} \rightarrow \mathbf{V}$ to be "differentiable"?

We suppose that $(\mathbf{V}, \|\cdot\|)$ is a *normed VS*. For a fnc $f: \mathbb{R} \rightarrow \mathbf{V}$ at a point $\tau \in \mathbb{R}$, we can make sense of the difference-quotient

$$1d: \frac{f(\tau + h) - f(\tau)}{h}, \quad \text{for non-zero } h \in \mathbb{R}.$$

Sending $h \rightarrow 0$ might give a $\|\cdot\|$ -limit; if so, we call the limit $f'(\tau)$.

Consider normed VSes $\mathbf{V}, \mathbf{W}, \mathbf{X}$, a fnc $\Omega: \mathbf{V} \times \mathbf{W} \rightarrow \mathbf{X}$, and a point $P := (\mathbf{v}, \mathbf{w})$ in $\mathbf{V} \times \mathbf{W}$. Then Ω is "(jointly) continuous at P " if:

For all sequences $\mathbf{a}_n \rightarrow \mathbf{v}$ in \mathbf{V} , and $\mathbf{b}_n \rightarrow \mathbf{w}$ in \mathbf{W} ,

1e: sequence

$$\Omega(\mathbf{a}_n, \mathbf{b}_n) \text{ tends to } \Omega(\mathbf{v}, \mathbf{w}) \text{ in } \mathbf{X}.$$

2: Product-rule Theorem. Consider normed vector-spaces $\mathbf{V}, \mathbf{W}, \mathbf{X}$ and differentiable functions $\alpha: \mathbb{R} \rightarrow \mathbf{V}$ and $\beta: \mathbb{R} \rightarrow \mathbf{W}$. Suppose $\llbracket \cdot, \cdot \rrbracket$ is a bilinear map $\mathbf{V} \times \mathbf{W} \rightarrow \mathbf{X}$. If $\llbracket \cdot, \cdot \rrbracket$ is (jointly) continuous, then

$$f(t) := \llbracket \alpha(t), \beta(t) \rrbracket$$

is differentiable, and

$$*: \llbracket \alpha, \beta \rrbracket' = \llbracket \alpha, \beta' \rrbracket + \llbracket \alpha', \beta \rrbracket. \quad \diamond$$

Pf. Fix $\tau \in \mathbb{R}$ and take a non-zero h . Then $f(\tau + h) - f(\tau)$ equals

$$\begin{aligned} & \llbracket \alpha(\tau + h), \beta(\tau + h) \rrbracket - \llbracket \alpha(\tau + h), \beta(\tau) \rrbracket \\ & + \llbracket \alpha(\tau + h), \beta(\tau) \rrbracket - \llbracket \alpha(\tau), \beta(\tau) \rrbracket. \end{aligned}$$

Using linearity in each argument separately, $f(\tau + h) - f(\tau)$ equals

$$\left\llbracket \alpha(\tau + h), \frac{\beta(\tau + h) - \beta(\tau)}{h} \right\rrbracket + \left\llbracket \frac{\alpha(\tau + h) - \alpha(\tau)}{h}, \beta(\tau) \right\rrbracket$$

Sending $h \rightarrow 0$ yields (*), courtesy the (joint) continuity. \blacklozenge

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