

Please. Do *not* approx.: If your result is “ $\sin(\sqrt{\pi})$ ” then write that rather than .9797... Use “ $f(x)$ notation” when writing fncs; in particular, for trig and log fncs. E.g, write “ $\sin(x)$ ” rather than the horrible $\sin x$ or $[\sin x]$. Write expressions unambiguously e.g, “ $1/a + b$ ” should be bracketed either $[1/a] + b$ or $1/[a + b]$. (Be careful with **negative** signs!) Short answer: Show no work.

A6: Please write **DNE** in a blank if the described object does not exist or if the indicated operation cannot be performed.

a $A := \begin{bmatrix} \sqrt{2} & 0 & -\sqrt{3} \\ 0 & -1 & 5 \end{bmatrix}$. Then $A^2 =$ _____.

b $M := \begin{bmatrix} -4 & 7 \\ 1 & 2 \end{bmatrix}$. Compute M^{-1} over these three fields.
[Write your \mathbb{Z}_p answers using symmetric residues.]

Over \mathbb{Z}_5 : $M^{-1} =$ _____ . Over \mathbb{Z}_7 : $M^{-1} =$ _____ .

Over \mathbb{Q} : $M^{-1} =$ _____ .

c $\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}^{16} =$ _____ .

d,e Let $P: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be orthogonal projection on the slope=5 line through the origin. W.r.t. the std basis,

then, the 2×2 matrix $[P]_{\mathcal{E}}^{\mathcal{E}} =$ _____ .

A7: Here, let **AT** mean “Always True”, **AF** mean “Always False” and **Nei** mean “Neither always true nor always false”. Below, **v, w, x** repr. *distinct, non-zero* vectors in \mathbb{R}^4 , a \mathbb{R} -VS. Please circle the correct response:

y1 If $\mathbf{x} \notin \text{Spn}\{\mathbf{v}, \mathbf{w}\}$ then $\{\mathbf{v}, \mathbf{w}, \mathbf{x}\}$ is linearly independent. AT AF Nei

y2 Collection $\{\mathbf{0}, \mathbf{x}\}$ is linearly-indep. AT AF Nei

y3 $\text{Spn}\{\mathbf{v}, \mathbf{w}, \mathbf{x}, \mathbf{v} + 2\mathbf{w} + 3\mathbf{x}\}$ is all of \mathbb{R}^4 . AT AF Nei

y4 If none of $\mathbf{v}, \mathbf{w}, \mathbf{x}$ is a multiple of the other vectors, then $\{\mathbf{v}, \mathbf{w}, \mathbf{x}\}$ is linearly independent. AT AF Nei

A8: Let $R := \begin{bmatrix} \sqrt{3} & 1 \\ -1 & \sqrt{3} \end{bmatrix}$. Then

$$R^{147} = \begin{bmatrix} & \\ & \end{bmatrix}.$$

[Hint: The linear trn R is a rotation followed by a dilation.]

A9: A system of 3 linear equations in unknowns x_1, \dots, x_5 reduces to the augmented matrix

$$\left[\begin{array}{ccccc|c} 1 & 1 & 0 & 0 & 1 & 12 \\ 0 & 0 & 1 & 0 & -8 & 34 \\ 0 & 0 & 0 & 1 & 5 & -56 \end{array} \right], \text{ which is in RREF. Please } \boxed{\text{circle}} \text{ each pivot entry.}$$

OYOP, describe the *general solution* in this form,

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} ? \\ ? \\ ? \\ ? \\ ? \end{bmatrix} + \alpha \begin{bmatrix} ? \\ ? \\ ? \\ ? \\ ? \end{bmatrix} + \beta \begin{bmatrix} ? \\ ? \\ ? \\ ? \\ ? \end{bmatrix} + \gamma \begin{bmatrix} ? \\ ? \\ ? \\ ? \\ ? \end{bmatrix} + \dots$$

where each $\alpha, \beta, \gamma, \delta, \dots$ is a free variable (either x_1 or... or x_5), and each column vector has specific numbers in it. $\text{Dim}(\text{SolnFlat}) =$ _____ .

A10: OASSOP, write out the following sentences, and complete them to give the correct definitions. Be specific with phrases “every”, “all”, “some”, “there exists”, etc.. *Avoid* the word “any”.

A (possibly infinite) set $\mathcal{S} \subset \mathbf{V}$ of vectors is **linearly dependent** IFF...

A $K \times N$ matrix U is in **reduced row echelon form** IFF...

End of A-InClass

A-Home: _____ 255pts

A6: _____ 50pts

A7: _____ 20pts

A8: _____ 20pts

A9: _____ 40pts

A10: _____ 30pts

Total: _____ 415pts

Please **PRINT** your *name* and *ordinal*. Ta:

Ord: _____

HONOR CODE: “I have neither requested nor received help on this exam other than from my professor.”

Signature: _____
Filename: Classwork/LinearAlg/LinA2005t/a-cl.LinA2005t.

latex
As of: Monday 31Aug2015. Typeset: 16Mar2016 at 00:29.